

Anisotropic Goal-Oriented Mesh Adaptation in Firedrake

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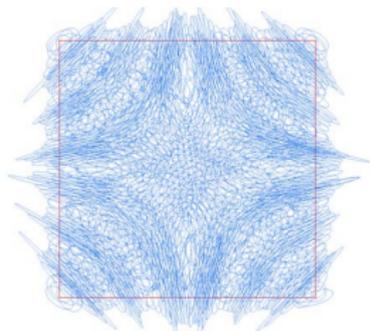
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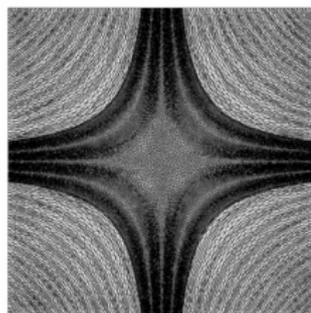
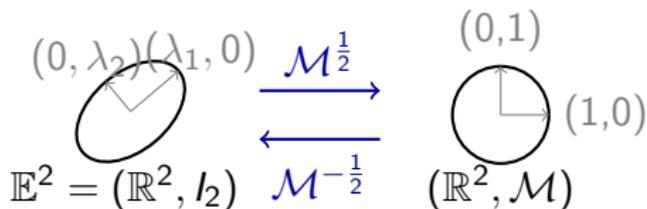
Firedrake '19, Durham

Metric-Based Mesh Adaptation.

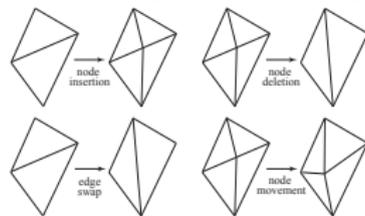
Riemannian **metric fields** $\mathcal{M} = \{\mathcal{M}(\mathbf{x})\}_{\mathbf{x} \in \Omega}$ are SPD $\forall \mathbf{x} \in \mathbb{R}^n$.
 \therefore Orthogonal eigendecomposition $\mathcal{M}(\mathbf{x}) = V\Lambda V^T$.



Steiner ellipses [Barral, 2015]



Resulting mesh [Barral, 2015]



The Hessian.

Consider interpolating $u \approx \mathcal{I}_h u \in \mathbb{P}1$.

It is shown in [Frey and Alauzet, 2005] that

$$\|u - \Pi_h u\|_{\mathcal{L}^\infty(K)} \leq \gamma \max_{\mathbf{x} \in K} \max_{\mathbf{e} \in \partial K} \mathbf{e}^T |H(\mathbf{x})| \mathbf{e}$$

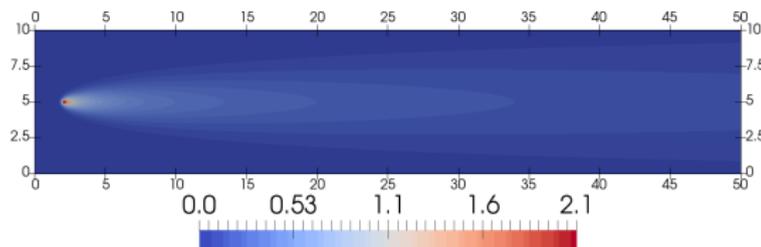
where $\gamma > 0$ is a constant related to the spatial dimension.

A metric tensor $\mathcal{M} = \{\mathcal{M}(\mathbf{x})\}_{\mathbf{x} \in \Omega}$ may be defined as

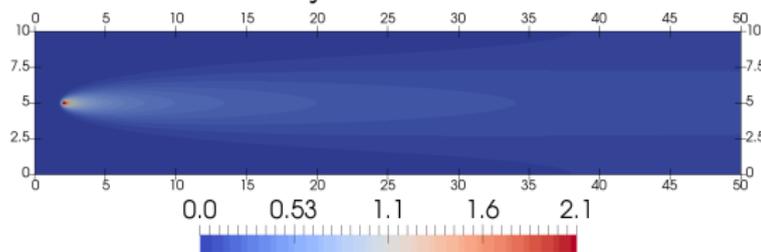
$$\mathcal{M}(\mathbf{x}) = \frac{\gamma}{\epsilon} |H(\mathbf{x})|,$$

where $\epsilon > 0$ is the tolerated error level.

Point Discharge with Diffusion



Analytical solution.



Finite element forward solution.

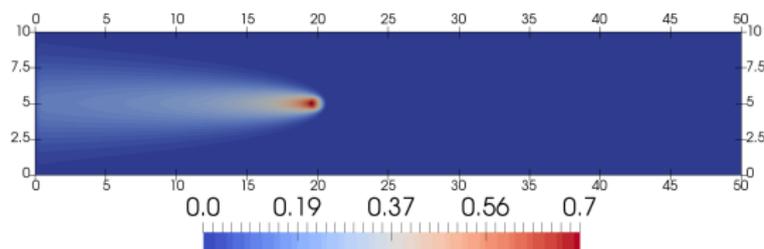
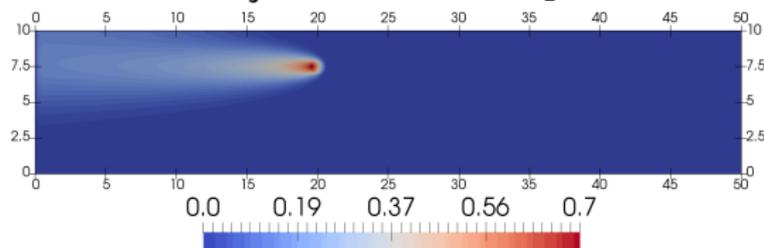
(Presented on a 1,024,000 element uniform mesh.)

Test case taken from
TELEMAC-2D Validation Document 7.0
[\[Riadh et al., 2014\]](#).

$$\left\{ \begin{array}{l} \mathbf{u} \cdot \nabla \phi - \nabla \cdot (\nu \nabla \phi) = f \\ \nu \hat{\mathbf{n}} \cdot \nabla \phi|_{\text{walls}} = 0 \\ \phi|_{\text{inflow}} = 0 \end{array} \right.$$

$$f = \delta(x - 2, y - 5)$$

Point Discharge with Diffusion: Adjoint Problem

Adjoint solution for J_1 .Adjoint solution for J_2 .

(Presented on a 1,024,000 element uniform mesh.)

$$J_i(\phi) = \int_{R_i} \phi \, dx$$

$$R_1 = B_{\frac{1}{2}}((20, 5))$$

$$R_2 = B_{\frac{1}{2}}((20, 7.5))$$

Point Discharge with Diffusion: Convergence

Elements	$J_1(\phi)$	$J_1(\phi_h)$	$J_2(\phi)$	$J_2(\phi_h)$
4,000	0.20757	0.20547	0.08882	0.08901
16,000	0.16904	0.16873	0.07206	0.07205
64,000	0.16263	0.62590	0.06924	0.06922
256,000	0.16344	0.16343	0.06959	0.06958
1,024,000	0.16344	0.16345	0.06959	0.06958

$J_i(\phi)$: analytical solutions

$J_i(\phi_h)$: $\mathbb{P}1$ finite element solutions

Dual Weighted Residual (DWR).

Given a PDE $\Psi(u) = 0$ and its adjoint written in Galerkin forms

$$\begin{aligned}\rho(u_h, v) &:= L(v) - a(u_h, v) = 0, & \forall v \in V_h \\ \rho^*(u_h^*, v) &:= J(v) - a(v, u_h^*) = 0, & \forall v \in V_h\end{aligned}$$

\implies **a posteriori** error results [[Becker and Rannacher, 2001](#)]

$$J(u) - J(u_h) = \rho(u_h, u^* - u_h^*) + R^{(2)}$$

$$J(u) - J(u_h) = \frac{1}{2}\rho(u_h, u^* - u_h^*) + \frac{1}{2}\rho^*(u_h^*, u - u_h) + R^{(3)}$$

[Remainders $R^{(2)}$ and $R^{(3)}$ depend on errors $u - u_h$ and $u^* - u_h^*$.]

DWR Integration by Parts

$$J(u) - J(u_h) = \rho(u_h, u^* - u_h^*) + R^{(2)}$$

Applying integration by parts (again) *elementwise*:

$$|J(u) - J(u_h)| \Big|_K \approx |\langle \Psi(u_h), u^* - u_h^* \rangle_K + \langle \psi(u_h), u^* - u_h^* \rangle_{\partial K}|.$$

- $\Psi(u_h)$ is the strong residual on K ;
- $\psi(u_h)$ embodies flux terms over elemental boundaries.

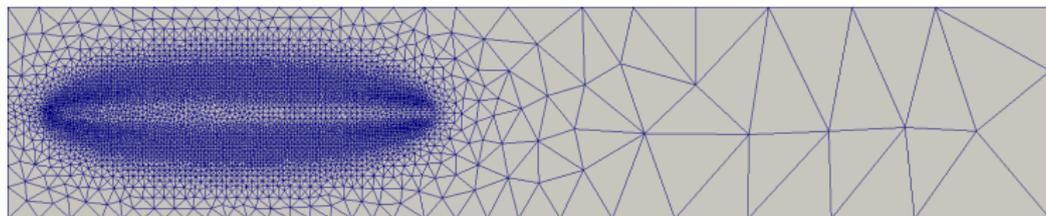
Isotropic Metric

$$|J(u) - J(u_h)| \Big|_K \approx \eta := |\langle \Psi(u_h), u^* - u_h^* \rangle_K + \langle \psi(u_h), u^* - u_h^* \rangle_{\partial K}|.$$

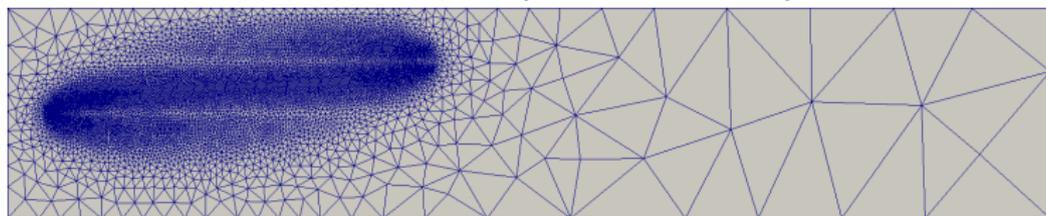
Isotropic case:

$$\mathcal{M} = \begin{bmatrix} \Pi_{\mathbb{P}1}\eta & 0 \\ 0 & \Pi_{\mathbb{P}1}\eta \end{bmatrix}.$$

Isotropic Meshes



Centred receiver (12,246 elements).



Offset receiver (19,399 elements).

A *posteriori* Approach

Motivated by the approach of [Power et al., 2006], consider the interpolation error:

$$|J(u) - J(u_h)| \approx |\langle \Psi(u_h), \underbrace{u^* - u_h^*}_{u^* - \Pi_h u^*} \rangle_K + \langle \psi(u_h), \underbrace{u^* - u_h^*}_{u^* - \Pi_h u^*} \rangle_{\partial K}|$$

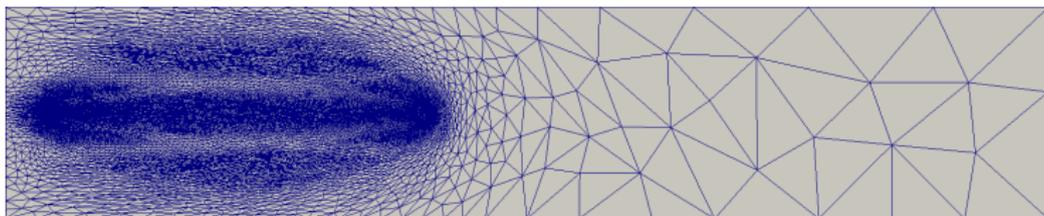
This suggests the node-wise metric,

$$\mathcal{M} = |\Psi(u_h)| |H(u^*)|,$$

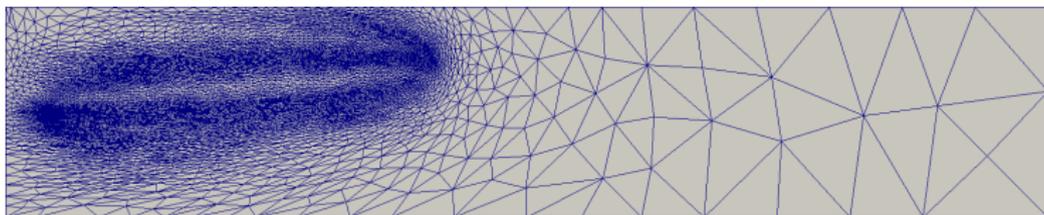
and correspondingly for the adjoint,

$$\mathcal{M} = |\Psi^*(u_h^*)| |H(u)|.$$

A posteriori Anisotropic Meshes



Centred receiver (16,407 elements).



Offset receiver (9,868 elements).

A priori Approach

Alternative **a priori** error estimate [[Loseille et al., 2010](#)]:

$$J(u) - J(u_h) = \langle (\Psi_h - \Psi)(u), u^* \rangle + \tilde{R}.$$

Assume we have the conservative form $\Psi(u) = \nabla \cdot \mathcal{F}(u)$, so

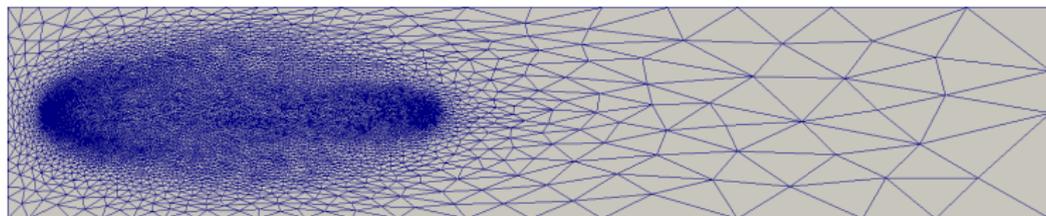
$$J(u) - J(u_h) \approx \langle (\mathcal{F} - \mathcal{F}_h)(u), \nabla u^* \rangle_{\Omega} - \langle \hat{n} \cdot (\bar{\mathcal{F}} - \bar{\mathcal{F}}_h(u)), u^* \rangle_{\partial\Omega}.$$

This gives Riemannian metric fields

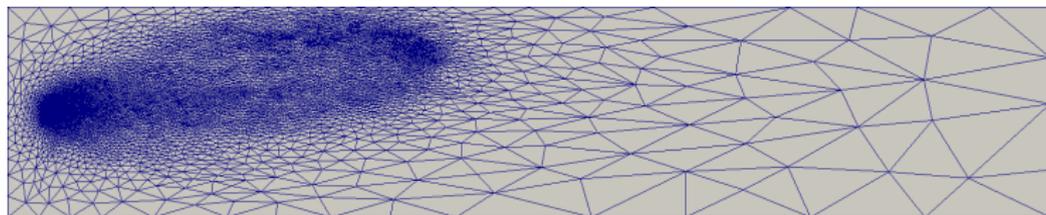
$$\mathcal{M}^{\text{volume}} = \sum_{i=1}^n |H(\mathcal{F}_i(u))| \left| \frac{\partial u^*}{\partial x_i} \right|,$$

$$\mathcal{M}^{\text{surface}} = |u^*| \left| \bar{H} \left(\sum_{i=1}^n \bar{\mathcal{F}}_i(u) \cdot n_i \right) \right|$$

A priori Anisotropic Meshes

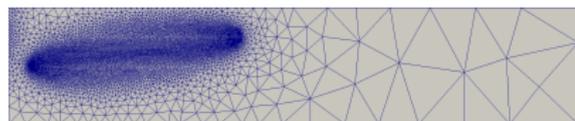


Centred receiver (44,894 elements).

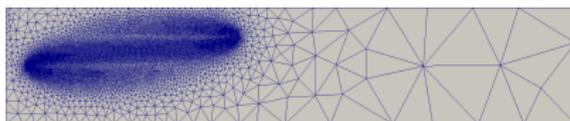


Offset receiver (29,143 elements).

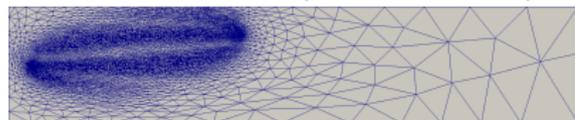
Meshes from Combined Metrics (Offset Receiver)



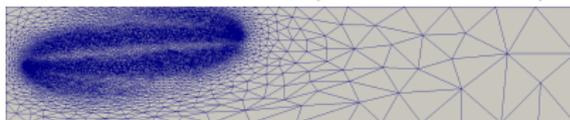
Averaged isotropic (13,980 elements).



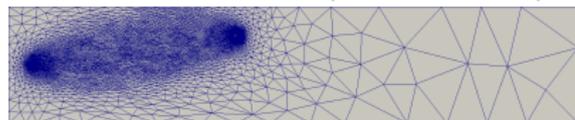
Superposed isotropic (19,588 elements).



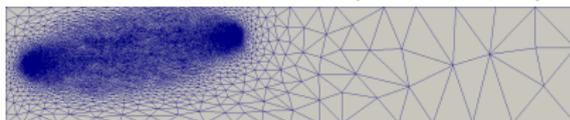
Averaged a posteriori (9,289 elements).



Superposed a posteriori (14,470 elems).

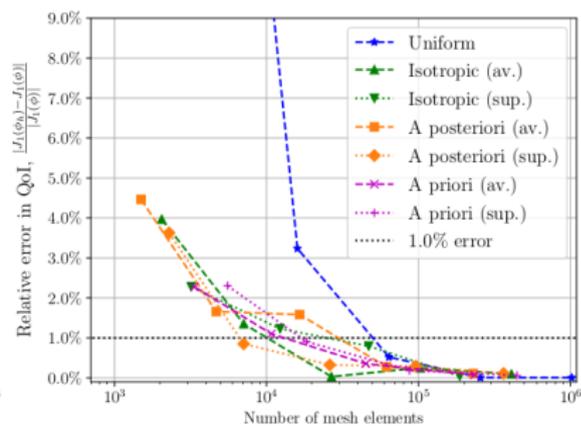
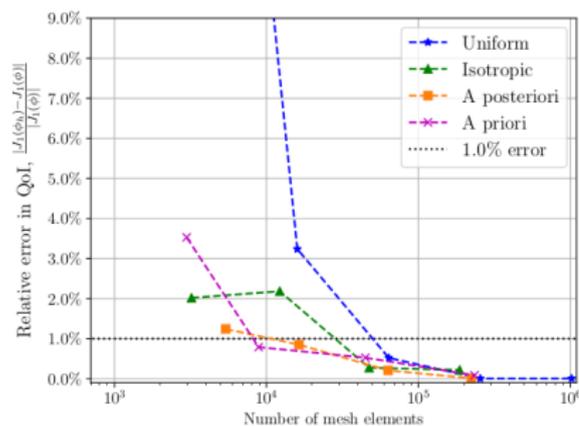


Averaged a priori (25,204 elements).

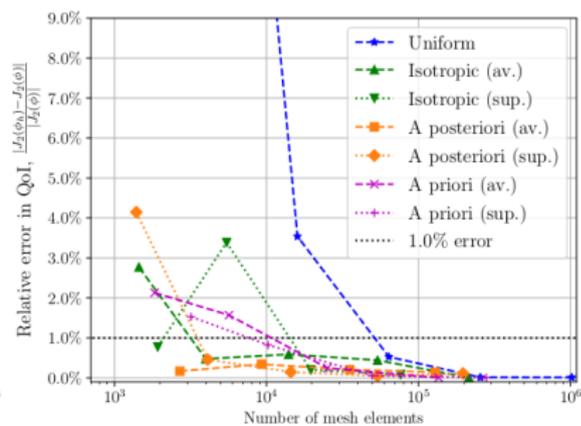
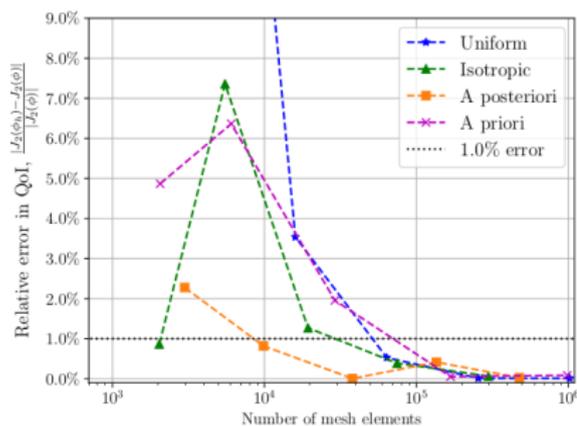


Superposed a priori (49,793 elements).

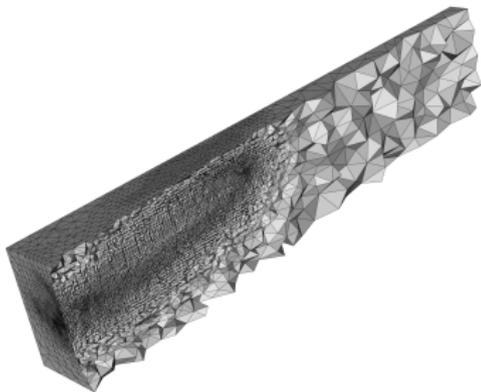
Convergence Analysis: Centred Receiver.



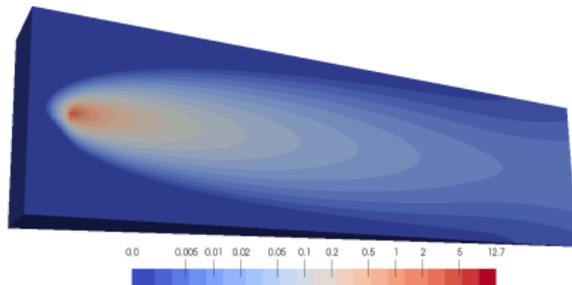
Convergence Analysis: Offset Receiver.



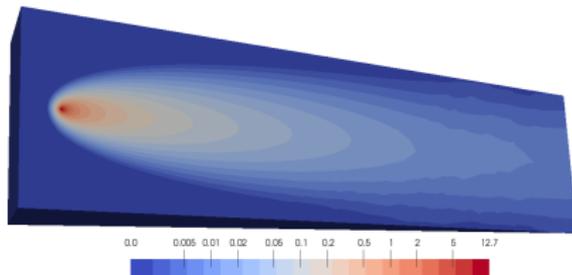
Three Dimensions.



Anisotropic mesh resulting from averaging a posteriori metrics.



Uniform mesh (1,920,000 elements).



Adapted mesh (1,766,396 elements).

Outlook.

To appear in proceedings of the 28th International Meshing Roundtable:

JW, N Barral, D Ham, M Piggott, “Anisotropic Goal-Oriented Mesh Adaptation in Firedrake” (2019).

Future work:

- Time dependent (tidal) problems.
- Other finite element spaces, e.g. DG.
- Boundary and flux terms for anisotropic methods.
- Realistic desalination application.

References

- Nicolas Barral. *Time-accurate anisotropic mesh adaptation for three-dimensional moving mesh problems*. PhD thesis, Université Pierre et Marie Curie, 2015.
- Roland Becker and Rolf Rannacher. An optimal control approach to a posteriori error estimation in finite element methods. *Acta Numerica 2001*, 10:1–102, May 2001. ISSN 0962-4929.
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- A Riadh, G Cedric, and MH Jean. TELEMAC modeling system: 2D hydrodynamics TELEMAC-2D software release 7.0 user manual. *Paris: R&D, Electricite de France*, page 134, 2014.
- Georgios Rokos and Gerard Gorman. Pragmatic–parallel anisotropic adaptive mesh toolkit. In *Facing the Multicore-Challenge III*, pages 143–144. Springer, 2013.

Metric Combination.

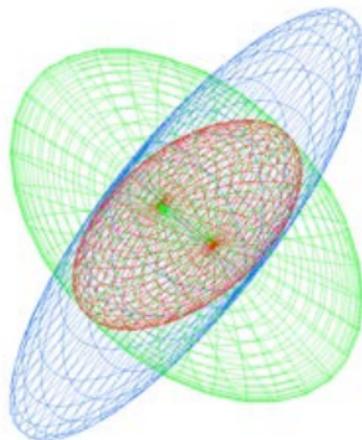
Consider metrics \mathcal{M}_1 and \mathcal{M}_2 . How to combine these in a meaningful way?

Metric average:

$$\mathcal{M} := \frac{1}{2}(\mathcal{M}_1 + \mathcal{M}_2).$$

Metric superposition:

intersection of Steiner ellipses.



Metric superposition [[Barral, 2015](#)]

Double \mathcal{L}_2 projection

We recover $H = \nabla^T \nabla u$ by solving the auxiliary problem

$$\begin{cases} H = \nabla^T \mathbf{g} \\ \mathbf{g} = \nabla u \end{cases}$$

as

$$\int_{\Omega} \tau : H_h \, dx + \int_{\Omega} \operatorname{div}(\tau) : \mathbf{g}_h \, dx - \sum_{i=1}^n \sum_{j=1}^n \int_{\partial\Omega} (\mathbf{g}_h)_i \tau_{ij} n_j \, ds = 0, \quad \forall \tau$$

$$\int_{\Omega} \psi \cdot \mathbf{g}_h \, dx = \int_{\partial\Omega} u_h \psi \cdot \hat{\mathbf{n}} \, ds - \int_{\Omega} \operatorname{div}(\psi) u_h \, dx, \quad \forall \psi.$$

Accounting for Source Term

Forward equation:

$$\nabla \cdot \mathcal{F}(\phi) = f, \quad \mathcal{F}(\phi) = \mathbf{u}\phi - \nu \nabla \phi.$$

$$\mathcal{M} = |H(\mathcal{F}_1(\phi))| \left| \frac{\partial \phi^*}{\partial x} \right| + |H(\mathcal{F}_2(\phi))| \left| \frac{\partial \phi^*}{\partial y} \right| + |H(f)| |\phi^*|.$$

Adjoint equation:

$$\nabla \cdot \mathcal{G}(\phi^*) = g, \quad \mathcal{G}(\phi^*) = -\mathbf{u}\phi^* - \nu \nabla \phi^*,$$

$$\mathcal{M} = |H(\mathcal{G}_1(\phi^*))| \left| \frac{\partial \phi}{\partial x} \right| + |H(\mathcal{G}_2(\phi^*))| \left| \frac{\partial \phi}{\partial y} \right| + |H(g)| |\phi|,$$